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Exactly Solvable Models

Lecture 31

§ 9. Schur Processes

What's coming up:

- Schur measures
- Markov dynamics
- Plane partitions
- Large time limit of the process
- Gaussian Unitary Ensemble

Schur measure

We have seen previously that G_{SIT} (in the 6-vertex model) defines a random string S (given T).

We would like an analogue of this for our new functions G_{SIT} (in our 'other' 6-vertex model). However, these weights are not stochastic.

This motivates the introduction of the Schur measures.

There are three types:

(Ascending Schur Measure)

$$P(\emptyset < \lambda^{(1)} < \dots < \lambda^{(N)}) = \left[\prod_{i=1}^N \frac{S_{\lambda^{(i)}}}{S_{\lambda^{(i-1)}}}(x_i) \right] S_{\lambda^{(N)}}(z_1, \dots, z_n) \cdot \prod_{i=1}^N \prod_{j=1}^n (1 - x_i z_j)$$

(Measure on space of all partitions)

$$P(\lambda) = S_{\lambda}(x_1, \dots, x_N) S_{\lambda}(z_1, \dots, z_n) \prod_{i=1}^N \prod_{j=1}^n (1 - x_i z_j)$$

(Plane partition measure)

$$P(\emptyset \prec \lambda^{(1)} \prec \dots \prec \lambda^{(n)} \succ \dots \succ \lambda^{(N+n)} \succ \emptyset)$$

$$= \prod_{i=1}^N \frac{S_{\lambda^{(i)}}}{\lambda^{(i-1)}} (x_i) \prod_{j=1}^n \frac{S_{\lambda^{(N+j)}}}{\lambda^{(N+j+1)}} (z_j) \prod_{i=1}^N \prod_{j=1}^n (1 - x_i z_j)$$

There is a one-to-one correspondence between sequences of the above form and plane partitions.

Definition: A plane partition $\pi = \{ \pi_{i,j} \}_{i,j \geq 1} \subseteq \mathbb{Z}_{\geq 0}$ satisfies two defining properties:

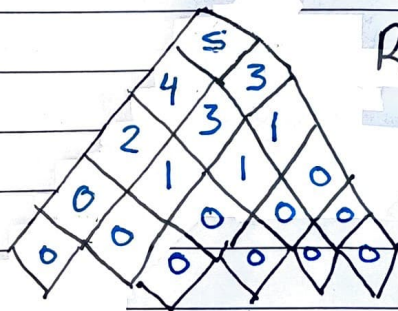
(1) If i, j are sufficiently large, then $\pi_{i,j} = 0$.

$$\left. \begin{array}{l} (2) \text{ (a) } \pi_{i,j} \geq \pi_{i,j+1} \\ \text{ (b) } \pi_{i,j} \geq \pi_{i+1,j} \end{array} \right\} \rightarrow \begin{array}{c} \pi_{i,j} \\ \parallel \\ \pi_{i+1,j} \end{array} \geq \begin{array}{c} \pi_{i,j} \\ \parallel \\ \pi_{i,j+1} \end{array}$$

In this way, we illustrate plane partitions as follows:



For example:



Reading the diagonals (verticals) we get:

$$\emptyset \prec (2) \prec (4 \ 1) \prec (5 \ 3) \succ (3 \ 1) \succ (1) \succ \emptyset$$

$$\text{Or, } \emptyset \prec \square \prec \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} \prec \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \succ \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} \succ \square \succ \emptyset$$

There is a nice degeneration of the plane partition measure.

Recall $S_{\lambda/\mu}(x) = \begin{cases} x^{|\lambda| - |\mu|} & , \lambda \prec \mu \\ 0 & , \text{otherwise} \end{cases}$

Using this fact, along with the specialization

$$x_N = q^{\frac{1}{2}}$$

$\vdots$

$$x_{N-1} = q^{\frac{3}{2}}$$

$\vdots$

$$x_i = q^{N-i+\frac{1}{2}}$$

$\vdots$

$$x_1 = q^{N-\frac{3}{2}}$$

$$z_1 = q^{\frac{1}{2}}$$

$\vdots$

$$z_2 = q^{\frac{3}{2}}$$

$\vdots$

$$z_i = q^{j-\frac{1}{2}}$$

$\vdots$

$$z_n = q^{n-\frac{1}{2}}$$

this is the principal specialization.

the offset is OK as Schur polynomials are homogeneous.

One may verify that, under this choice

$$\underline{P_{pp}(\pi)} = q^{|\pi|} \prod_{i=1}^N \prod_{j=1}^n (1 - q^{i+j-1})$$

where $|\pi| = \sum_{i,j} \pi_{i,j}$

This matches with a known generating series for plane partitions:

$$\sum_{\pi \in \mathbb{N} \times \mathbb{N} \text{ box}} q^{|\pi|} = \frac{1}{\prod_{i=1}^N \prod_{j=1}^n (1 - q^{i+j-1})}$$

Taking n, N to infinity,

$$\sum_{\pi} q^{|\pi|} = \frac{1}{\prod_{i=1}^{\infty} (1 - q^i)^i}$$

The ascending Schur measure and plane partition measure have a connection with Markov dynamics.

Definition

$$M_{x; \vec{z}}^{\uparrow}(\mu \rightarrow \lambda) = S_{\lambda/\mu}(x) \cdot \frac{S_{\lambda}(\vec{z})}{S_{\mu}(\vec{z})} \cdot \prod_{j=1}^{\infty} (1 - x z_j)$$

(One should check that, via the skew Cauchy identity, that $\sum_{\lambda} M_{x; \vec{z}}^{\uparrow}(\mu \rightarrow \lambda) = 1$)

Let $y \in \{z_1, z_2, \dots\}$.

$$M_{y; \vec{z}}^{\downarrow}(\lambda \rightarrow \mu) = S_{\lambda/\mu}(y) \cdot \frac{S_{\mu}(\vec{z} \setminus \{y\})}{S_{\lambda}(\vec{z})}$$

(One should check that, via the branching rule, that $\sum_{\mu} M_{y; \vec{z}}^{\downarrow}(\lambda \rightarrow \mu) = 1$)