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4th August 2025

Exactly Solvable Models

Filling in details of lecture 3

Define $T_a^N(u) = L_{a1}(u) \cdots L_{aN}(u)$.

Recall that

$$L_{aN}(u) = \begin{pmatrix} \begin{pmatrix} \sinh(u + \frac{\gamma}{2}) & \\ & \sinh(u - \frac{\gamma}{2}) \end{pmatrix}_N & \begin{pmatrix} \sinh(\gamma) & \\ & \sinh(u - \frac{\gamma}{2}) \end{pmatrix}_N \\ \begin{pmatrix} & \sinh(\gamma) \\ & \sinh(u + \frac{\gamma}{2}) \end{pmatrix}_N & \begin{pmatrix} \sinh(u - \frac{\gamma}{2}) & \\ & \sinh(u + \frac{\gamma}{2}) \end{pmatrix}_N \end{pmatrix}_a$$

So,

$$\frac{dL_{aN}(u)}{du} = \begin{pmatrix} \begin{pmatrix} \cosh(u + \frac{\gamma}{2}) & \\ & \cosh(u - \frac{\gamma}{2}) \end{pmatrix}_N & \begin{pmatrix} \cosh(u - \frac{\gamma}{2}) & \\ & \cosh(u + \frac{\gamma}{2}) \end{pmatrix}_N \\ \begin{pmatrix} \cosh(u - \frac{\gamma}{2}) & \\ & \cosh(u + \frac{\gamma}{2}) \end{pmatrix}_N & \begin{pmatrix} \cosh(u + \frac{\gamma}{2}) & \\ & \cosh(u - \frac{\gamma}{2}) \end{pmatrix}_N \end{pmatrix}_a$$

Substituting $u = \frac{\gamma}{2}$ gives

$$L_{aN}(u)|_{u=\frac{\gamma}{2}} = \sinh(\gamma) P_{aN}, \quad \frac{dL_{aN}(u)}{du} \Big|_{u=\frac{\gamma}{2}} = \begin{pmatrix} \begin{pmatrix} \cosh(\gamma) & \\ & 1 \end{pmatrix}_N & \begin{pmatrix} 1 & \\ & \cosh(\gamma) \end{pmatrix}_N \\ \begin{pmatrix} 1 & \\ & \cosh(\gamma) \end{pmatrix}_N & \begin{pmatrix} \cosh(\gamma) & \\ & 1 \end{pmatrix}_N \end{pmatrix}_a$$

Define $M_{aN} = \begin{pmatrix} \begin{pmatrix} \cosh(\gamma) & \\ & 1 \end{pmatrix}_N & \begin{pmatrix} 1 & \\ & \cosh(\gamma) \end{pmatrix}_N \\ \begin{pmatrix} 1 & \\ & \cosh(\gamma) \end{pmatrix}_N & \begin{pmatrix} \cosh(\gamma) & \\ & 1 \end{pmatrix}_N \end{pmatrix}_a$.

Using product rule, we thus get, if $N \geq 2$,

$$\begin{aligned} \frac{dT_a^N(u)}{du} &= \frac{d}{du} [L_{a1}(u) \cdots L_{aN-1}(u)] L_{aN}(u) \\ &\quad + L_{a1}(u) \cdots L_{aN-1}(u) \cdot \frac{d}{du} [L_{aN}(u)] \\ &= \frac{dT_a^{N-1}(u)}{du} \cdot L_{aN}(u) + T_a^{N-1}(u) \cdot \frac{dL_{aN}(u)}{du} \end{aligned}$$

Substituting $u = \frac{\gamma}{2}$ gives:

$$\left. \frac{dT_a^N(u)}{du} \right|_{u=\frac{\gamma}{2}} = \left. \frac{dT_a^{N-1}(u)}{du} \right|_{u=\frac{\gamma}{2}} \cdot L_{aN}(u) \Big|_{u=\frac{\gamma}{2}} + T_a^{N-1}(u) \Big|_{u=\frac{\gamma}{2}} \cdot \left. \frac{dL_{aN}(u)}{du} \right|_{u=\frac{\gamma}{2}}$$

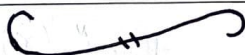
$$= \left. \frac{dT_a^{N-1}(u)}{du} \right|_{u=\frac{\gamma}{2}} \sinh(\gamma) P_{aN} + \sinh^{N-1}(\gamma) P_{a1} \dots P_{aN} M_{aN}$$

Iterating this $N-1$ times, we get

$$\left. \frac{dT_a^N(u)}{du} \right|_{u=\frac{\gamma}{2}} = \left. \frac{dT_a(u)}{du} \right|_{u=\frac{\gamma}{2}} \sinh^{N-1}(\gamma) P_{a2} \dots P_{aN} + \sum_{k=2}^N \sinh^{N-1}(\gamma) \left[P_{a1} \dots P_{a,k-1} \dots \right. \\ \left. \dots M_{ak} P_{a,k+1} \dots P_{aN} \right]$$

$$= M_{a1} \cdot \sinh^{N-1}(\gamma) P_{a2} \dots P_{aN} + \sum_{k=2}^N \sinh^{N-1}(\gamma) \left[P_{a1} \dots P_{a,k-1} M_{ak} P_{a,k+1} \dots P_{aN} \right]$$

$$= \sinh^{N-1}(\gamma) \sum_{k=1}^N \left[P_{a1} \dots P_{a,k-1} M_{ak} P_{a,k+1} \dots P_{aN} \right]$$



Next, let us find $\left. \frac{dt(u)}{du} \right|_{u=\frac{\gamma}{2}}$.

We have,

$$\left. \frac{dt(u)}{du} \right|_{u=\frac{\gamma}{2}} = \sinh^{N-1}(\gamma) \sum_{k=1}^N \text{tr}_a (P_{a1} \dots P_{a,k-1} M_{ak} P_{a,k+1} \dots P_{aN})$$

When $k=1$, we have, in the summand,

$$\begin{aligned}
 M_{a_1} P_{a_2} \cdots P_{a_N} &= M_{a_1} P_{23} \cdots P_{2N} P_{a_2} \\
 &= P_{23} \cdots P_{2N} M_{a_1} P_{a_2} \\
 &= P_{23} \cdots P_{2N} P_{a_2} M_{21} \\
 &= P_{23} \cdots P_{2N-1} P_{2N} P_{a_2} M_{21} \\
 &= P_{23} \cdots P_{2N-1} P_{a_N} M_{N1} P_{2N} \\
 &= P_{a_N} P_{23} \cdots P_{2N-1} M_{N1} P_{2N} \\
 &= P_{a_N} M_{N1} P_{23} \cdots P_{2N-1} P_{2N}
 \end{aligned}$$

So,

$$\text{tr}_a (M_{a_1} P_{a_2} \cdots P_{a_N}) = M_{N1} P_{23} \cdots P_{2N}$$

When $k \neq 1$,

$$\begin{aligned}
 \text{tr}_a (P_{a_1} \cdots P_{a_{k-1}} M_{a_k} P_{a_{k+1}} \cdots P_{a_N}) \\
 &= \text{tr}_a (P_{12} \cdots P_{1,k-1} M_{1,k} P_{1,k+1} \cdots P_{1N} P_{a_1}) \\
 &= P_{12} \cdots P_{1,k-1} M_{1,k} P_{1,k+1} \cdots P_{1N}
 \end{aligned}$$

This gives the result that:

$$\left. \frac{dt(u)}{du} \right|_{u=\frac{\tau}{2}} = \sinh^{N-1} \left[\sum_{k=2}^N (P_{12} \cdots P_{1,k-1} M_{1,k} P_{1,k+1} \cdots P_{1N}) + M_{N1} P_{23} \cdots P_{2N} \right]$$

Next,

$$\sinh(x) \frac{dt(u)}{du} \Big|_{u=\frac{x}{2}} t\left(\frac{x}{2}\right)^{-1}$$

$$= \left[\sum_{k=2}^N (P_{12} \cdots P_{1,k-1}) M_{1,k} (P_{1,k+1} \cdots P_{1,N}) + M_{N,1} P_{23} \cdots P_{2N} \right] (P_{1N} \cdots P_{12})$$

Now, we have, in the $k=1$ case:

$$\begin{aligned} M_{N,1} (P_{23} \cdots P_{2N}) (P_{1N} \cdots P_{12}) \\ &= M_{N,1} (P_{23} \cdots P_{2N-1}) (P_{2N} P_{1N}) (P_{1N-1} \cdots P_{12}) \\ &= M_{N,1} (P_{23} \cdots P_{2N-1}) (P_{12} P_{2N}) (P_{1N-1} \cdots P_{12}) \\ &= M_{N,1} (P_{12} \cdots P_{1N-1}) (P_{2N}) (P_{1N-1} \cdots P_{12}) \\ &= M_{N,1} (P_{12} \cdots P_{1N-1}) (P_{1N-1} \cdots P_{13}) (P_{2N} P_{12}) \\ &= M_{N,1} P_{12} P_{2N} P_{12} \\ &= M_{N,1} P_{1N} \end{aligned}$$

In the $k \neq 1$ case, we have

$$\begin{aligned} (P_{12} \cdots P_{1,k-1}) M_{1,k} (P_{1,k+1} \cdots P_{1,N}) (P_{1N} \cdots P_{12}) \\ &= (P_{12} \cdots P_{1,k-1}) M_{1,k} (P_{1,k+1} \cdots P_{1,N}) (P_{1N} \cdots P_{1,k+1}) (P_{1,k} \cdots P_{12}) \\ &= (P_{12} \cdots P_{1,k-1}) M_{1,k} (P_{1,k} \cdots P_{12}) \\ &= (P_{12} \cdots P_{1,k-2}) (P_{1,k-1} M_{1,k}) (P_{1,k} \cdots P_{12}) \\ &= (P_{12} \cdots P_{1,k-2}) (M_{k-1,k} P_{1,k-1}) (P_{1,k} \cdots P_{12}) \\ &= M_{k-1,k} (P_{12} \cdots P_{1,k-1}) (P_{1,k} \cdots P_{12}) \\ &= M_{k-1,k} (P_{12} \cdots P_{1,k-1}) (P_{1,k}) (P_{1,k-1} \cdots P_{12}) \end{aligned}$$

Now, use the relation that $M_{ac} = P_{ab} M_{bc} P_{ab}$

So,

$$\begin{aligned} (P_{12} \cdots P_{1,k-1}) M_{1,k} (P_{1,k+1} \cdots P_{1,N}) (P_{1N} \cdots P_{12}) \\ &= M_{k-1,k} (P_{12} \cdots P_{1,k-2}) (P_{1,k-1} P_{1,k} P_{1,k-1}) (P_{1,k-2} \cdots P_{12}) \\ &= M_{k-1,k} (P_{12} \cdots P_{1,k-2}) P_{k,k-1} (P_{1,k-2} \cdots P_{12}) \end{aligned}$$

$$= M_{R-1,k} P_{k,k-1}.$$

So, we have found that

$$\sinh(\sigma) \frac{dt(u)}{du} \Big|_{u=\frac{\sigma}{2}} t\left(\frac{\sigma}{2}\right)^{-1} \\ = M_{N,1} P_{1,N} + \sum_{k=2}^N M_{k-1,k} P_{k,k-1}$$

$$= \sum_{k=1}^N M_{k-1,k} P_{k,k-1}, \quad \text{where we have made the identification } 0 \equiv N.$$

Now, recall that $P_{k,k-1} = P_{k-1,k}$, and so

$$M_{k-1,k} P_{k,k-1} = \begin{pmatrix} \begin{pmatrix} \cosh(\sigma) & \\ & 1 \end{pmatrix}_k & \begin{pmatrix} & \\ & \end{pmatrix}_k \\ \begin{pmatrix} & \\ & \end{pmatrix}_k & \begin{pmatrix} & \\ \cosh(\sigma) & \end{pmatrix}_k \end{pmatrix}_{k-1} \begin{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}_k & \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}_k \\ \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}_k & \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}_k \end{pmatrix}_{k-1} \\ = \begin{pmatrix} \begin{pmatrix} \cosh(\sigma) & 0 \\ 0 & 0 \end{pmatrix}_k & \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}_k \\ \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}_k & \begin{pmatrix} 0 & 0 \\ 0 & \cosh(\sigma) \end{pmatrix}_k \end{pmatrix}_{k-1}$$

So,

$$\sinh(\sigma) \frac{dt(u)}{du} \Big|_{u=\frac{\sigma}{2}} t\left(\frac{\sigma}{2}\right)^{-1} = \sum_{k=1}^N \begin{pmatrix} \begin{pmatrix} \cosh(\sigma) & 0 \\ 0 & 0 \end{pmatrix}_k & \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}_k \\ \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}_k & \begin{pmatrix} 0 & 0 \\ 0 & \cosh(\sigma) \end{pmatrix}_k \end{pmatrix}_{k-1}$$

as required.

Finally, we show that this expression is in fact equal to the Hamiltonian.

We have that: (defining $\Delta = e^\tau + e^{-\tau}$)

$$\begin{aligned}
 & (\sigma_{n-1}^x \sigma_n^x + \sigma_{n-1}^y \sigma_n^y + \Delta \sigma_{n-1}^z \sigma_n^z)^{\frac{1}{2}} \\
 &= \frac{1}{2} \left(\begin{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}_n & \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}_n \\ \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}_n & \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}_n \end{pmatrix}_{n-1} + \begin{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}_n & \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}_n \\ \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}_n & \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}_n \end{pmatrix}_{n-1} + \begin{pmatrix} \begin{pmatrix} \Delta & 0 \\ 0 & 0 \end{pmatrix}_n & \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}_n \\ \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}_n & \begin{pmatrix} 0 & 0 \\ 0 & \Delta \end{pmatrix}_n \end{pmatrix}_{n-1} \right) \\
 &= \frac{1}{2} \begin{pmatrix} \begin{pmatrix} \Delta & 0 \\ 0 & 0 \end{pmatrix}_n & \begin{pmatrix} 0 & 0 \\ 2 & 0 \end{pmatrix}_n \\ \begin{pmatrix} 0 & 2 \\ 0 & 0 \end{pmatrix}_n & \begin{pmatrix} 0 & 0 \\ 0 & \Delta \end{pmatrix}_n \end{pmatrix}_{n-1} \\
 &= \begin{pmatrix} \begin{pmatrix} \cosh(\tau) & 0 \\ 0 & 0 \end{pmatrix}_n & \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}_n \\ \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}_n & \begin{pmatrix} 0 & 0 \\ 0 & \cosh(\tau) \end{pmatrix}_n \end{pmatrix}_{n-1}
 \end{aligned}$$

and so we are done.